1A2(1st Day - AM2)																										
		A		В	С		D	E		F	G		н	I		J		K	L		М	N		0		
1		Mechanism and Control for Force :	Mech	S		M				Parall				1				Medic Ro Mec		Medica ar	Nano				1	
2				Mechanism and Control for Actuator	Mechanism and Control for Actuator		Mechanism and Control for Actuator	Sense, I		Sense, I	el Robo and its		Robo		2	-		-	Medical and Welfare Robotics and Mechatronics(2)		Medical and Welfare Robotics and Mechatronics(2)	Nano/Micro Manipulation System Co		Nan		2
3								Motion a		Motion a	Parallel Robot/Mechanisms and its Control		Parallel Robot/Mechanisms Digital and its Control		3	Medical a		/ledical a	Velfare and cs(2)					Nano/Micro Manipulation System		3
4								Sense, Motion and Measurement		nd Meas					4	and Welfare		and Welf	Univ		obotics ②					4
5				Tacti Force :				suremen		Sense, Motion and Measurement	Digital				5			Medical and Welfare Robotics and Mechatronics ${\mathbb Q}$	Universal Design	5	Univ De:					5
6		Tactile and orce Sensing		Tactile and orce Sensing ①	tor	tor	tor	t			Digital Human		Digital Human		6	Robotics and			esign		Universal Design			Co		6
															7	d Mecha		d Mecha	0		0	mmunica		mmunica		7
7		Tactile and Force Sensing(1)		Tactile and Force Sensing(1)	Robo		Robots for Amusement and Entertainment	(O		(A)	Digital				8	Mechatronics 2		tronics(ognitive		ognitive	Communication Robot		Communication Robot		8
8					Robots for Amusement and Entertainment			sense, M Measu		sense, M Measu			Digital Human	Dig	9			(D)	Cognitive Robotics		Cognitive Robotics	bot		bot		9
9								Sense, Motion and Measurement		Sense, Motion and Measurement				Digital Human	10				SS		SS					10
10										Ιď	Digital Human		nan	nan												
11																										
12					ıment																					