

ISMB15 Time Table

Wednesday, Aug. 3

9:30	16:30	City Tour		
17:30	20:00	Registration@Mojiko Hotel		
18:00	20:00	Welcome Reception@Mojiko Hotel		

Thursday, Aug. 4

8:00	18:00	Registration			
		Room A (2F)	Room B (4F)	Room C (4F)	Room D (4F)
8:30	8:40	Opening			
8:40	8:50		Break 10 min		
8:50	10:10	Applications I	Devices	SBMs I	
10:10	10:40		Coffee Break 30 min		
10:40	12:00	Applications II	Control I	SBMs II	
		Lunchtime Presentation (12:30 - 12:50) 1)Tianjin Emaging Technology 2) SINKAWA Electric	Lunch 60 min		Exhibition
12:00	13:00				
13:00	13:40	Keynote I			
13:40	14:00		Take Photo & Break 20 min		
14:00	15:40	Applications III	Control II	SBMs III	
15:40	16:10		Coffee Break 30 min		
16:10	17:50	Design & Modeling I	Control III	SBMs IV	
17:30	22:00	Dinner for All in Mojiko Area			
18:30		Meeting for International Advisory Committee Members (by Bus)			

Friday, Aug. 5

8:00	12:00	Registration			
		Room A (2F)	Room B (4F)	Room C (4F)	Room D (4F)
8:30	9:30	Design & Modeling II	Self-Sensing I	SBMs V	
9:30	9:40		Break 10 min		
9:40	10:40	Design & Modeling III	Self-Sensing II	SBMs VI	
10:40	11:10		Coffee Break 30 min		
11:10	11:50	Keynote II			
12:05	17:15	Technical Tour			
18:00	20:00	Banquet@Mojiko Hotel (2F)			

Saturday, Aug. 6

8:00	12:00	Registration			
		Room A (2F)	Room B (4F)	Room C (4F)	Room D (4F)
8:30	9:50	Design & Modeling IV	Control IV	SBMs VII	
9:50	10:20		Coffee Break 30 min		
10:20	12:00	Design & Modeling V	Control V	SBMs VIII, PMBs I	
12:00	13:00		Lunch 60 min		
13:00	13:40	Keynote III			
13:40	13:50		Break 10 min		
13:50	15:10	Backup Bearings I	Control VI	PMBs II	
15:10	15:40		Coffee Break 30 min		
15:40	17:20	Backup Bearings II	Control VII	PMBs III	
17:20	18:30	Farewell Party@Mojiko Hotel			
18:30	21:00	Summer Festival @Nishikokura (by JR Train)			

KEYNOTES

Keynote Address I

Time/Room : Thursday, Aug. 4, 13:00 - 13:40 / Room A (2F)

Chairs: Hannes Bleuler, Richard M. Stephan, Haruhiko Suzuki

Related technologies of magnetic bearings and their applications

Toshiro Higuchi, University of Tokyo (emeritus professor), Ritsumeikan University (visiting professor), Japan

Since about 35 years ago, I have been involved in various kinds of research works about magnetic bearings and their related technologies. The belief summary is presented in this speech. The subjects are as follows. Estimation and compensation of unbalance; Periodic learning control; Clean robot with magnetic bearing joints; Magnetically Suspended Stepping Motors; Magnetic supported intelligent hand for automated precise assembly; Magnetic levitation by pinning effect of HTS and soft magnetic material; Electrostatic suspension and drive of thin glass sheet and wafer; Magnetic suspension by motion control of magnet; Magnetic suspension by composite of magnetostrictive and piezoelectric materials; Non-contact handling by tilt control and automatic object release.

Keynote Address II

Time/Room Friday, Aug. 5, 11:10 - 11:50 / Room A (2F)

Chairs: Wolfgang Amrhein, Mimpei Morishita

The Short History of the Superconducting Maglev - Changes in Null flux circuit and Pole pitch -

Junichi Kitano, Maglev Systems Development Division, Central Japan Railway Company, Japan

The first-ever concept of the Superconducting Maglev train was proposed by Dr. Powell and Dr. Danby in 1966. After the half century development, the basic technologies were established and daily operation of 500km/h by a 7-car train set continues in the Yamanashi Test Line. The world speed record of 603km/h was established in April 2015 and the cumulative distance traveled reached 1,500,000km at the end of March 2016. Also, the Chuo Shinkansen connecting Tokyo and Nagoya in 40 minutes, is now under construction. In this paper, a brief overview of changes in a Null flux circuit and a pole pitch of the Miyazaki Test Track and the Yamanashi Test Line is presented.

Keynote Address III

Time/Room Saturday, Aug. 6, 13:00 - 13:40 / Room A (2F)

Chairs: Lichuan Li, Toru Masuzawa

Application of Flywheel Energy Storage Systems as an Industrial Product

Larry Hawkins, Director of Technology for Magnetic Bearings and Co-Founder, Calnetix Technologies, USA

Flywheel Energy Storage Systems (FESS) have now progressed from a promising technology to the core element of true commercial products. FESS are now part of the critical power supply in many diverse applications – from data centers to health care facilities, and from the gaming industry to broadcast studios. Flywheel systems are improving energy demand efficiency in mobile cranes and in metro rail stations. Advances in magnetic bearings and in efficient power conversions devices have played key roles. This talk discusses several aspects of industrial flywheel systems – the basics of flywheel energy storage, key technologies, how it is applied, and how flywheels tradeoff against competing technologies. Key trends and requirements in the common application areas are also discussed.

Thursday, Aug. 4

Session	T1A	Applications I	T1B	Devices	T1C	SBMs I
Time/Room Session Chairs		8:50 - 10:10 / Room A (2F) Bruno Dehez, Frank Wörlich		8:50 - 10:10 / Room B (4F) Hirochika Ueyama, Matthias Hofer		8:50 - 10:10 / Room C (4F) Junichi Asama, Satoshi Ueno
8:50 9:10	T1A1	The development of the flywheel energy storage system applying the high temperature superconducting magnetic bearing - The examination of a demonstration machine by having it charged/discharged with solar photovoltaic power - 10077 *Motohiko Sugino, Ken Nagashima, Masafumi Ogata, Tomohisa Yamashita, Hitoshi Matsue, Yoshiki Miyazaki (Railway Technical Research Institute), Shinichi Horiuchi (Yamanashi Pref. Gov.), Japan	T1B1	Theoretical basics and closed loop control design of stray-flux-based measurement systems for magnetic bearings	T1C1	20 Years Bearingless Slice Motor - its Developments and Applications
9:10 9:30	T1A2	The development of the flywheel energy storage system applying the high temperature superconducting magnetic bearing (second report) - The development and the performance evaluation examination of the SMB for the FESS demonstration machine - 10145 Motohiko Sugino, *Yoshiki Miyazaki, Ken Nagashima, Masafumi Ogata, Tomohisa Yamashita, Hitoshi Matsue (Railway Technical Research Institute), Taro Matsuoka, Kengo Nakao (Furukawa Electric), Japan	T1B2	Estimation of Magnetic Center Location in Radial Active Magnetic Bearings Through a Pull Test	T1C2	Impact of Inclination of Teeth for Bearingless Motor with Non-contact Power Supply
9:30 9:50	T1A3	High temperature active magnetic bearings in industrial steam turbines 10119 *Stephan Duesterhaupt, Holger Neumann, Torsten Rottenbach, Christian Vanek, Frank Wörlich (Zittau/Görlitz University of Applied Sciences), Germany	T1B3	Automated Design of AMB Rotor Systems with Standard Drive, Control Software and Hardware Technologies	T1C3	Torque interaction of the drive and active radial magnetic bearing in an ultra-high speed spinning ball motor 10091 *Marcel Schuck (Swiss Federal Institute of Technology, Zurich), Daniel Steinert (Levitronix), Johann Walter Kolar (ETH), Switzerland
9:50 10:10	T1A4	Thermal model for a low-speed flywheel in medium vacuum 10071 *Virginie Kluyskens, Maxence Van Beneden, Bruno Dehez (Université Catholique de Louvain), Belgium	T1B4	The Electro Magnetic Compatibility Analysis and Experiment of the electronic system in AMB 10084 *Yan Zhou, Ni Mo, Guojun Yang, Zhengang Shi, Lei Zhao (Tsinghua University), China		

Thursday, Aug. 4

Session	T2A	Applications II	T2B	Control I	T2C	SBMs II
Time/Room Session Chairs		10:40 - 12:00 / Room A (2F) Richard Jayawant, Naohiko Takahashi		10:40 - 12:00 / Room B (4F) Ilmar Santos, Toru Watanabe		10:40 - 12:00 / Room C (4F) Wolfgang Gruber, Yohji Okada
10:40 11:00	T2A1	Zero Power Levitation Control of a Magnetically Levitated Linear Slider Platform with Non-Contact Power Supply 10164 *Buddhika Imantha Annasiwaththa, Koichi Oka (Kochi University of Technology), Japan	T2B1	Design of Robust AMB Controllers for Rotors Subjected to Varying and Uncertain Seal Forces 10048 *Jonas Lauridsen, Ilmar Santos (Technical University of Denmark), Denmark	T2C1	Efficiency of buried permanent magnet type 5kW and 50kW high-speed bearingless motors with 4-pole motor windings and 2-pole suspension windings 10112 *Rafal Piotr Jastrzebski, Pekko Jaatinen (Lappeenranta University of Technology), Akira Chiba (Tokyo Institute of Technology), Olli Pyrhonen (LUT), Finland
11:00 11:20	T2A2	Numerical and experimental assessment of a large industrial thrust bearing 10013 *Benjamin Defoy (GE Oil & Gas), Xavier de Lepine, Lionel Broussard (GE Energy Power Conversion), Mohamed Osama (GE Global Research), France	T2B2	Experimental Verification of Adaptive Control in Active Magnetic Bearings 10094 *Li Li, Stephan Duesterhaupt, Frank Worlitz (Zittau/Gorlitz University of Applied Sciences), Germany	T2C2	Using feed-forward back propagation for Rotor Flux Estimation of a Bearingless Induction Motor applied in the Speed Vector Control 10054 J. S. B. Lopes, J. D. Fernandes, F. E. C Souza, L. P. Santos, J. A. de Paiva (Federal Institute of Education, Science and Technology of Rio G. do Norte), *Andres Ortiz Salazar (Federal University of Rio Grande do Norte), Brazil
11:20 11:40	T2A3	Design of a Mobile Flywheel Energy Storage driven by a Switched Reluctance Machine 10016 *Fabian Lorenz, Ralf Werner (Chemnitz University of Technology), Germany	T2B3	Improvement of Active Magnetic Bearing system using Jerk Feedback Controller for an Elastic Rotor 10047 *Hirokazu Tomono, Hiroyuki Fujisaki, Toru Watanabe (Nihon University), Kazuto Seto (Seto-Engineering Office), Japan	T2C3	Unbalance Compensation for Lorentz-force-type Self-Bearing Motor 10137 *Satoshi Ueno, Ryosuke Otani, Changan Jiang (Ritsumeikan University), Japan
11:40 12:00	T2A4	Design and Qualification Testing of Active Magnetic Bearings for High-Temperature Gas-Cooled Reactors 10076 *Zenglin Guo (Waukesha Magnetic Bearings), Guohui Zhou (Shanghai Blower Works), Richard R. Shultz (Waukesha Magnetic Bearings), Minlong Qian (Shanghai Blower Works), Liang Zhu (Tsinghua University), China	T2B4	Characteristic Model Based All-Coefficient Adaptive Control of a High-Speed Desorption Pump Supported by AMBs 10004 *Long Di (University of Virginia), Chao Yun Chen, Chung Hsien Lin (Industrial Technology Research Institute), Zongli Lin (UVA), USA	T2C4	Evaluation of Motor Losses and Efficiency in a d-q Axis Current Control Bearingless Motor 10165 *Masahide Ooshima, Yuto Gomi (Tokyo University of Science, Suwa), Japan

Thursday, Aug. 4

Session		T3A	Applications III	T3B	Control II	T3C	SBMs III
Time/Room			14:00 - 15:40 / Room A (2F)		14:00 - 15:40 / Room B (4F)		14:00 - 15:40 / Room C (4F)
Session Chairs			Zenglin Guo, Virginie Kluykens		Wataru Hijikata, Kai Zhang		Akira Chiba, Changan Jiang
14:00	14:20	T3A1	Design and Experiment of 300 HP Class Turbo Compressor with Hybrid Magnetic Bearings 10009 *Cheol Hoon Park, Jun Young Park (Korea Institute of Machinery and Materials), South Korea	T3B1	Stabilization of Self-excited Vibration in Rotor-oil Film Bearing System by Utilizing Radial Magnetic Bearing 10096 Wataru Tsunoda, Wataru Hijikata, *Tadahiko Shinshi (Tokyo Institute of Technology), Hiroyuki Fujiwara, Osami Matsushita (National Defense Academy), Japan	T3C1	Automated parameter identification platform for magnetic levitation systems: case bearingless machine 10041 *Pekko Jaatinen, Teemu Sillanpaa, Rafal P. Jastrzebski, Eerik Sikanen, Olli Pyrhonen (Lappeenranta University of Technology), Finland
14:20	14:40	T3A2	Design and commissioning of a 3.3 MW motor-driven compressor fully supported on active magnetic bearings 10043 *Richard Jayawant, Andrea Masala (Waukesha Magnetic Bearings), UK	T3B2	Characteristic quantities of active magnetic bearings 10154 *Gerald Jungmayr, Edmund Marth (Johannes Kepler University Linz), Robert Santner (Linz Center of Mechatronics), Wolfgang Amrhein (JKU Linz), Austria	T3C2	Basic Calculation of Axial Force and Torque with Permeance Method in One-Axis Actively Positioned Single-Drive Bearingless Motor. 10113 *Itsuki Shimura, Hiroyuki Sugimoto, Akira Chiba (Tokyo Institute of Technology), Japan
14:40	15:00	T3A3	Commissioning of Off-Shore Gas Compressor with 9-Axes Magnetic Bearing System: Controller Design 10129 *Beat Aeschlimann, Michael Hubatka, Michael Ernst Peter, Robert Stettler, Reza Housseini (Mecos AG), Switzerland	T3B3	Fractional Order Control of Rotor Suspension by Active Magnetic Bearings 10083 *Parinya Anantachaisilp (Royal Thai Air Force Academy), Zongli Lin (University of Virginia), Thailand	T3C3	Control of a single parallel winding bearingless machine 10075 *Nicolas Schneider (University of Nottingham), Puvan Arumugam (Force Engineering), Herve Morvan, Seamus Garvey (University of Nottingham), Tahar Hamiti (VEDECOM), UK
15:00	15:20	T3A4	Initial Levitation Testing and Design of Magnetic Bearing System for High Speed Turbo-Aerator 10134 Simon Mushi, Brad Nichols, Tim Dimond, *Paul Allaire, Jianming Cao (Rotor Bearing Solutions International), Richard Newark, Nigel Lloyd, Nick Schulze, Brad Billow, Farshad Daneshvar, Omar Alshahrani (Kinetic Traction Systems), USA	T3B4	Robust controller design for AMB levitation recovery 10080 *Alexander H. Pesch (Hofstra University), Jerzy T. Sawicki (Cleveland State University), USA	T3C4	Modelling and Control Design Simulations of Permanent Magnet Flux-Switching Linear Bearingless Motor 10072 *Rafal Piotr Jastrzebski, Pekko Jaatinen, Olli Pyrhonen (Lappeenranta University of Technology), Finland
15:20	15:40	T3A5	Design of Active Magnetic Radial and Thrust Bearings for High Speed Turbo Aerator 10135 *Paul Allaire, Jianming Cao, Tim Dimond, Simon Mushi, Saeid Dousti (Rotor Bearing Solutions International), Richard Newark, Nigel Lloyd, Omar Alshahrani, Farshad Daneshvar (Kinetic Traction Systems), USA	T3B5	Robust Adaptive Control of Permanent Magnetic Suspension System Using Variable Flux Path Control Method 10121 *Feng Sun, Pengpeng Xia, Xingwei Sun, He Lu (Shenyang University of Technology), Koichi Oka (Kochi University of Technology), China	T3C5	Development of New Propulsion System for Magnetically Levitated Vehicles 10008 *Toshio Kakinoki, Hitoshi Yamaguchi, Tomoaki Murakami, Eiichi Mukai, Hiroyuki Nishi (Sojo University), Japan

Thursday, Aug. 4

Session	T4A	Design & Modeling I	T4B	Control III	T4C	SBMs IV
Time/Room Session Chairs		16:10 - 17:50 / Room A (2F) Beat Aeschlimann, Koichi Oka		16:10 - 17:50 / Room B (4F) Parinya Anantachaisilp, Alexander Hans Pesch		16:10 - 17:30 / Room C (4F) Masahide Ooshima, Andres Ortiz Salazar
16:10 - 16:30	T4A1	Laboratory Tests on an Interconnected Four Poles Magnetic Bearing 10074 <i>Domingos F. B. David, Jose A. Santisteban (Fluminense Federal University), *Afonso Celso D. N. Gomes (Federal University of Rio de Janeiro), Brazil</i>	T4B1	A study on zero-bias simple adaptive control AMB system 10111 <i>*Dong Liang, Daisaku Ozaki, Astushi Kubo, Ryouichi Takahata (JTEKT), Kenzo Nonami (Chiba University), Japan</i>	T4C1	Simplified Configuration of a Two-DOF Actively Controlled Bearingless Motor Using Two H-Bridges 10139 <i>*Junichi Asama, Kenta Sasaki, Takaaki Oiwa (Shizuoka University), Akira Chiba (Tokyo Institute of Technology), Japan</i>
16:30 - 16:50	T4A2	Thermal Limit Analysis of Radial AMB by Using Finite Difference Method 10089 <i>*Chi Ting Yeh, Chung Hsien Lin (Industrial Technology Research Institute), Taiwan</i>	T4B2	Analytical Asymmetric Air Gap Model for Active Magnetic Thrust Bearings of Mixed Materials Including Eddy Currents 10017 <i>*Robert Seifert, Wilfried Hofmann (Dresden University of Technology), Germany</i>	T4C2	Modeling of a Single Point Suspended Electromagnetic Suspension Carrier System - Study on Rolling Motion - 10156 <i>*Shogo Hida, Mimpei Morishita (Kogakuin University), Japan</i>
16:50 - 17:10	T4A3	Turbomolecular pumps on active conical magnetic bearings 10093 <i>Nicola Amati, *Angelo Bonfitto, Lester Daniel Suarez, Andrea Tonoli (Polytechnic University of Turin), Italy</i>	T4B3	H-infinity controller design for active magnetic bearing systems considering nonlinear vibrational rotordynamics 10090 <i>*Matthew Owen Thomas Cole (Chiang Mai University), Chakkapong Chamroon (University of Phayao), Patrick Sean Keogh (University of Bath), Thailand</i>	T4C3	A Self-bearing 8/6 Switched Reluctance Motor 10036 <i>*Aino Manninen (VTT Technical Research Centre of Finland), Victor Mukherjee (Aalto University), Jenni Pippuri (VTT Technical Research Centre of Finland), Kari Tammi (Aalto University), Finland</i>
17:10 - 17:30	T4A4	Mechanical design of reconfigurable active magnetic bearing test rig 10100 <i>*Erik Sikanen, Rafal Jastrzebski, Pekko Jaatinen, Teemu Sillanpaa, Alexander Smirnov, Jussi Sopanen, Olli Pyrhonen (Lappeenranta University of Technology), Finland</i>	T4B4	Control of Magnetic Bearings with Rotor-Mounted Accelerometers 10144 <i>*Samuel Jimenez, Patrick Keogh (University of Bath), UK</i>	T4C4	A Novel Bearingless Flux-Switching Permanent Motor 10079 <i>*Chenyin Zhao, Huangqiu Zhu, Jintao Ju (Jiangsu University), China</i>
17:30 - 17:50	T4A5	Design of Three-pole Radial-axial HMB with Independent Radial and Axial Carrying Capacity 10078 <i>*Jintao Ju, Huangqiu Zhu, Chenyin Zhao (Jiangsu University), China</i>	T4B5	A smooth switch between different unbalance control parameters in rotor systems with active magnetic bearings 10002 <i>*Kai Zhang, Jiuchao Yin, Xingjian Dai (Tsinghua University), China</i>		

Friday, Aug. 5

Session	F1A	Design & Modeling II	F1B	Self-Sensing I	F1C	SBMs V	
Time/Room		8:30 - 9:30 / Room A (2F)		8:30 - 9:30 / Room B (4F)		8:30 - 9:30 / Room C (4F)	
Session Chairs		Toshiro Higuchi, Suyuan Yu		Myounggyu D. Noh, Feng Sun		Nobuyuki Kurita, Hubert Mitterhofer	
8:30	8:50	F1A1	(Invited Paper) Low Cost Active Magnetic Bearings - Concepts and Examples	F1B1	New Results on the Robustness of Self-sensing Magnetic Bearings	F1C1	Design Consideration for Performance Improvement in One-Axis Actively Positioned Single-Drive Bearingless Motor
		10133	*Paul Allaire, Brad Nichols, Tim Dimond, Jianming Cao, Simon Mushi (Rotor Bearing Solutions International), USA	10030	*Markus Hutterer, Matthias Hofer, Manfred Schroedl (Vienna University of Technology), Austria	10138	*Hiroya Sugimoto, Itsuki Shimura, Akira Chiba (Tokyo Institute of Technology), Japan
8:50	9:10	F1A2	Design Aspects of AMBs for High-Speed Permanent Magnet Synchronous Machine	F1B2	Smooth voltage controller and observer for a three-pole active magnetic bearing system	F1C2	High Torque Bearingless Flux-Switching Slice Drive
		10014	*Alexander Smirnov, Nikita Uzhegov (Lappeenranta University of Technology), Toni Hartikainen (Aurelia Turbines), Juha Pyrhonen, Olli Pyrhonen (LUT), Finland	10102	*Shyh-Leh Chen, Yung-Ho Hsiao (National Chung Cheng University), Taiwan	10136	*Karlo Radman (Linz Center of Mechatronics), Wolfgang Gruber (Johannes Kepler University Linz), Neven Bulic (University of Rijeka), Austria
9:10	9:30	F1A3	Design of AMB and Rotordynamics for a 30kW, 60 000 rpm Permanent-magnet Machine	F1B3	PCB Integrated Differential Current Slope Measurement for Position-Sensorless Controlled Radial Active Magnetic Bearings	F1C3	Homopolar Hysteresis Bearingless Motors
		10053	*Ziyuan Huang, Yun Le, Bangcheng Han (Beihang University), China	10018	*Matthias Hofer, Markus Hutterer, Manfred Schroedl (Vienna University of Technology), Austria	10148	*Minkyun Noh (Massachusetts Institute of Technology), Wolfgang Gruber (Johannes Kepler University Linz), David L. Trumper (MIT), USA

Friday, Aug. 5

Session	F2A	Design & Modeling III	F2B	Self-Sensing II	F2C	SBMs VI	
Time/Room		9:40 - 10:40 / Room A (2F)		9:40 - 10:40 / Room B (4F)		9:40 - 10:40 / Room C (4F)	
Session Chairs		Paul Allaire, Takeshi Mizuno		Yuichi Ariga, Shyh-Leh Chen		Rafal Piotr Jastrzebski, Hiroya Sugimoto	
9:40	10:00	F2A1 10141	Design of an Enlarged Wind Tunnel System for Spinning Body Using Magnetic Suspension <i>*Shahajada Mahmudul Hasan, Takeshi Mizuno, Masaya Takasaki, Yuji Ishino (Saitama University), Japan</i>	F2B1 10023	Algorithms for self-sensing magnetic bearings using current signals and least square identification <i>*Daniel Franz, Michael Richter, Stephan Rinderknecht (Technical University of Darmstadt), Germany</i>	F2C1 10035	Flux-Linkage Model Including Cross Saturation for a Bearingless Synchronous Reluctance Motor <i>*Seppo E. Saarakkala, Maksim Sokolov, Victor Mukherjee (Aalto University), Jenni Pippuri (VTT Technical Research Centre of Finland), Kari Tammi, Anouar Belahcen, Marko Hinkkanen (Aalto University), Finland</i>
10:00	10:20	F2A2 10015	Design and evaluation of high-speed solid rotor induction machine supported by AMBs with a multidisciplinary tool <i>*Alexander Smirnov, Nikita Uzhegov, Teemu Sillanpaa, Juha Pyrhonen, Olli Pyrhonen (Lappeenranta University of Technology), Finland</i>	F2B2 10019	Application of Soft Magnetic Composites (SMCs) in Position-Sensorless Controlled Radial Active Magnetic Bearings <i>*Matthias Hofer, Markus Hutterer, Manfred Schroedl(Vienna University of Technology), Austria</i>	F2C2 10105	Basic Design of the Maglev Pump for Total Artificial Heart by using Double Stator Type Axial Self-bearing Motor <i>*Nobuyuki Kurita, Takeo Ishikawa, Naoki Saito (Gunma University), Toru Masuzawa (Ibaraki University), Japan</i>
10:20	10:40	F2A3 10085	The design of a centrifugal blower rotor with magnetic bearings based on rotor dynamics <i>*Junting Wang, Jiageng Su, Suyuan Yu (Tsinghua University), China</i>	F2B3 10033	An analytical frequency-domain model of self-sensing magnetic bearing: modulation approach <i>*Jie Yu, Changsheng Zhu (Zhejiang University), China</i>	F2C3 10099	Active suppression of structural force harmonics in PM bearingless motors <i>*Blaise Lapotre, Babak Nahid-Mobarakeh, Noureddine Takorabet, Farid Meilbody-Tabar (University of Lorraine), Ramdane Lateb, Joaquim Da Silva (SKF Magnetic Mechatronics), France</i>

Saturday, Aug. 6

Session		S1A Design & Modeling IV		S1B Control IV		S1C SBMs VII	
Time/Room	Session Chairs	8:30 - 9:50 / Room A (2F) Mochimitsu Komori, Alexander Smirnov		8:30 - 9:50 / Room B (4F) Jarir Mahfoud, Mitsuo Hirata		8:30 - 9:50 / Room C (4F) Shujin Liu, Hiroyuki Onuma	
8:30	8:50	S1A1	Basic Study on Active Magnetic Bearing working in Liquid Nitrogen	S1B1	Rotordynamic Behavior and Rigid Mode Vibration Control by Hybrid Foil-Magnetic Bearing System	S1C1	Experimental Verification of a Model-Based Zero and Low-Speed Angle Observer for Bearingless Permanent Magnet Machines
		10147	Mochimitsu Komori, Kenshi Watanabe, *Hiroyisa Katou, Ken-ichi Asami, Nobuo Sakai (Kyushu Institute of Technology), Japan	10161	*Sena Jeong (Korea Institute of Science and Technology), Doyoung Jeon (Sogang University), Yongbok Lee (KIST), South Korea	10039	*Tobias Wellerdieck, Pascal Reichmuth (Federal Institute of Technology, Zurich), Daniel Steinert (Levitronix), Johann W. Kolar (ETH), Switzerland
8:50	9:10	S1A2	Six Pole type Hybrid Magnetic Bearing for Turbo-Machinery	S1B2	Control of an AMB to Zero Static Force	S1C2	Analysis of Electromagnetic Force Ripple on the Rotor of a Bearingless Synchronous Reluctance Motor
		10028	*Yohji Okada, Masaki Touno, Ken-Ichi Matsuda, Ryou Kondo (Ibaraki University), Takashi Todaka (Oita University), Japan	10026	Michael Caple, *Eric Maslen, Jacquelyn Nagel, Jacob Wild (James Madison University), USA	10003	*Victor Mukherjee (Aalto University), Aino Manninen, Jenni Pippuri (VTT Technical Research Centre of Finland), Anouar Belahcen (Aalto University, Tallinn University of Technology), Finland
9:10	9:30	S1A3	Updating the model of a rotor with surface mounted permanent magnets in an active magnetic bearing rotor system	S1B3	On the dynamics of rotating machinery supported by AMB during base motion	S1C3	Magnetic Levitation Performance of Miniaturized Magnetically Levitated Motor with 5-DOF Active Control
		10010	*Jouni Vuojolainen, Alexander Smirnov, Rafal Jastrzebski, Teemu Sillanpaa, Behnam Ghalamchi (Lappeenranta University of Technology), Toni Hartikainen (Aurelia Turbines), Olli Pyrhonen (LUT), Finland	10044	*Clement Jarroux, Jarir Mahfoud, Regis Dufour (University of Lyon), Benjamin Defoy, Thomas Alban (GE Oil & Gas), France	10106	*Masahiro Osa, Toru Masuzawa, Takuwa Saito (Ibaraki University), Eisuke Tatsumi (National Cerebral and Cardiovascular Center Research Institute), Japan
9:30	9:50	S1A4	Parameter Identification for Stiffness and Damping in AMB-Flexible Rotor System	S1B4	Unbalance force observer and compensator of magnetic bearings supporting centrifugal compressor	S1C4	5-Degree of Freedom Active Position Control of an Axial Self-bearing Motor with Six Concentrated Stator Windings
		10027	*Kejian Jiang (Zhejiang Sci-Tech University), Changsheng Zhu (Zhejiang University), China	10107	*Kexiang Li, Zhiquan Deng, Chengzi Liu, Jie Zhou, Jiaxi He (Nanjing University of Aeronautics and Astronautics), Jiaqiang Ning (Nanjing Engineering Institute of Aircraft Systems), China	10142	*Changan Jiang, Kazuaki Andou, Satoshi Ueno (Ritsumeikan University), Japan

Saturday, Aug. 6

Session	S2A	Design & Modeling V	S2B	Control V	S2C	SBMs VIII, PMBs I
Time/Room Session Chairs		10:20 - 12:00 / Room A (2F) Toshihiko Sugiura, Jin Zhou		10:20 - 12:00 / Room B (4F) Shai Arogeti, Tetsuzo Sakamoto		10:20 - 12:00 / Room C (4F) Gerald Jugmayr, Tadahiko Shinshi
10:20 10:40	S2A1	On system identification for active magnetic bearings at nonzero speeds 10025 *Adolfo Anta, Rosa Castane Selga, Mohamed Osama (GE Global Research), Thomas Alban, Benjamin Defoy (GE Oil & Gas), Germany	S2B1	Direct Field Control of AMBs using Flux Feedback based on Integrable Hall Sensors 10150 *Falk Bahr (Dresden University of Technology), Ingolf Moench (IFW Dresden), Daniel Ernst, Thomas Zerna (TUD), Oliver G. Schmidt (IFW Dresden), Wilfried Hofmann (TUD), Germany	S2C1	Development of radial type self-bearing motor for small centrifugal blood pump 10116 *Hiroyuki Onuma (National Institute of Technology, Ibaraki College), Toru Masuzawa, Michiko Murakami (Ibaraki University), Japan
10:40 11:00	S2A2	Using a pseudorandom binary sequence for rotor-bearing system identification in active magnetic bearing rotor systems 10011 *Jouni Vuojolainen, Rafal Jastrzebski, Olli Pyrhonen (Lappeenranta University of Technology), Finland	S2B2	Modeling and Control of Magnetic Bearings With Nonlinear Magnetization (Simulation vs. Experiment) 10049 Ali Gerami, *Roger Fittro, Carl Knospe (University of Virginia), USA	S2C2	Development of a Centrifugal Cryogenic Fluid Pump using an Axial Self-bearing Motor 10143 *Ryo Takeda, Satoshi Ueno, Changan Jiang (Ritsumeikan University), Japan
11:00 11:20	S2A3	Identification of Parameters in Active Magnetic Bearing Systems 10069 *Andreas Jauemik Voigt (Lloyd's Register Consulting, Technical University of Denmark), Jonas Lauridsen, Christian Mandrup-Poulsen (DTU), Kenny Krogh Nielsen (Lloyd's Register Consulting), Ilmar F. Santos (DTU), Denmark	S2B3	Bias Flux Compensation in the 'Side-By-Side' Combination Radial/Axial Homopolar PM-Biased Active Magnetic Bearing 10073 *Alexei Filatov, Larry Hawkins, Chinmay Ukidve (Calnetix Technologies), USA	S2C3	Stability improvement of passively stabilized degrees of freedom in magnetically levitated systems 10126 *Hubert Mitterhofer (Linz Center of Mechatronics), Gerald Jungmayr (Johannes Kepler University Linz), Austria
11:20 11:40	S2A4	Identification of Active Magnetic Bearing Systems Utilizing a Modulating Function Technique 10088 Olga Gavrilenko, Johann Reger, *Dennis Roeser, Thomas Sattel (Ilmenau University of Technology), Germany	S2B4	Duality parameter of Approximate Dual Control for Electromagnetic Suspension 10155 *Kento Osako, Tetsuzo Sakamoto (Kyushu Institute of Technology), Japan	S2C4	Dynamic characterization of electrodynamic bearings combined with active magnetic dampers 10101 *Qingwen Cui (Swiss Federal Institute of Technology in Lausanne), Fabrizio Impinna, Lester D. Suaerz Cabrera, Joaquim G. Detoni, Nicola Amati, Andrea Tonoli (Polytechnic University of Turin), Hannes Bleuler (EPFL), Switzerland
11:40 12:00	S2A5	Identification of Dynamic Parameters for Flexible Rotor AMBs System Considering Residual Unbalances 10087 *Yuanping Xu, Jin Zhou, Chaowu Jin, Longxiang Xu (Nanjing University of Aeronautics and Astronautics), China	S2B5	Precision positioning oriented modeling of electromagnetic actuator 10109 *Sergei Basovich, Yonattan Menaker, Shai Arogeti (Ben-Gurion University of the Negev), Israel	S2C5	An Axial flow blood pump with magnetic fluid mixed support 10132 *Shuqin Liu (Shandong University), H. Ming Chen (Shandong engineering research center for magnetic bearings), China

Saturday, Aug. 6

Session		S3A	Backup Bearings I	S3B	Control VI	S3C	PMBs II
Time/Room			13:50 - 15:10 / Room A (2F)		13:50 - 15:10 / Room B (4F)		13:50 - 15:10 / Room C (4F)
Session Chairs			Matthew Owen Thomas Cole, Kejian Jiang, Lukas Quurck		Zongli Lin, Eric Harvey Maslen		Masahiro Osa, Juan de Santiago
13:50	14:10	S3A1	Influence of Unbalance Levels on Nonlinear Dynamics of a Rotor-Backup Rolling Bearing System	S3B1	Advanced Control Performance in Compressor Surge	S3C1	Evaluation of the electrodynamic forces in a high-speed permanent magnet machines with rotor eccentricity
		10124	*Cesar Fonseca, Ilmar Santos (Technical University of Denmark), Hans Weber (Pontifical Catholic University of Rio de Janeiro), Denmark	10029	Emil Kurvinen (FS Dynamics), *Roger Fittro (University of Virginia), Eric Maslen (James Madison University), Finland	10045	Corentin Dumont (Universite catholique de Louvain), Adrien Gilson (University of Franche-Comte), Virginie Kluyskens (UCL), Christophe Espanet (UFC), *Bruno Dehez (UCL), Belgium
14:10	14:30	S3A2	Dynamic Conditions to Destabilize Persistent Rotor/Touchdown Bearing Contact in AMB Systems	S3B2	Autobalancing of AMB Systems Using a Differential Regulator Based Output Regulation Approach	S3C2	Round Layout Halbach Array using Cylinder Shaped Permanent Magnets
		10163	*Patrick Sean Keogh (University of Bath), Matthew Owen Thomas Cole (Chiang Mai University), UK	10005	*Long Di (University of Virginia), Se Young Yoon (University of New Hampshire), Zongli Lin (UVA), USA	10158	*Haruhiko Suzuki, Masatoshi Kanamaru, Mizuki Sato, Shogo Tokunaga, Shuichiro Kainuma, Atsushi Ito (National Institute of Technology, Fukushima College), Japan
14:30	14:50	S3A3	Transient Simulation of magnetic bearing and backup bearing interaction in a high speed rotary atomizer subjected to impulsive loads	S3B3	Inertial Centering of Magnetically Suspended Flexible Rotors	S3C3	A systematic approach for modeling and identification of eddy current dampers in rotordynamic applications
		10051	*Larry Hawkins, Zhiyang Wang (Calnetix Technologies), Vishal Wadhvani (Dedert Corporation), USA	10117	*Rami Levy, Shai Arogeti (Ben-Gurion University of the Negev), Israel	10092	*Qingwen Cui (Swiss Federal Institute of Technology in Lausanne), Maria di Napoli, Joaquim Detoni, Nicola Amati, Andrea Tonoli (Polytechnic University of Turin), Italy
14:50	15:10	S3A4	An Investigation into Backup Bearing Life using Quantified Rotor Delevitation Severity Indicators	S3B4	Field Dynamic Balancing System Based on Labview in AMB-Flexible Rotor System	S3C4	Design of Permanent Magnet Levitation Roller for Belt Conveyer
		10006	*Jacob Martinus Gouws, Jan Jacobus Janse van Rensburg (North-West University of Potchefstroom), South Africa	10062	*Jingjing Zhao, Zhe Sun, Xunshi Yan, Zhengang Shi (Tsinghua University), China	10034	Huachun Wu, Yongwu Ren, Shiping Yang (Wuhan University of Technology), Nianxian Wang (Wuhan University of Science and Technology), *Chunsheng Song, Yefa Hu (WUT), China

Saturday, Aug. 6

Session	S4A	Backup Bearings II	S4B	Control VII	S4C	PMBs III
Time/Room Session Chairs		15:40 - 17:20 / Room A (2F) Jan Jacobus Janse van Rensburg, Zixi Wang		15:40 - 17:20 / Room B (4F) Roger Fittoro, Patrick Sean Keogh		15:40 - 17:20 / Room C (4F) Alexei Filatov, Chunsheng Song
15:40 - 16:00	S4A1	Rotor Drop Analyses and Auxiliary Bearing System Optimization for AMB Supported Rotor/Experimental Validation - Part I: Analysis Method 10127 <i>Jianming Cao, *Paul Allaire, Timothy Dimond (Rotor Bearing Solutions International), JJ. Janse van Rensburg (North-West University of Potchefstroom), Christian Klatt (CEROBEAR), USA</i>	S4B1	Control of Flexible Rotor by Using Electromagnetic Actuators: Optimization of the Fuzzy Controller Gains 10021 <i>Michael Soler Beatty, *Jarir Mahfoud (University of Lyon), France</i>	S4C1	Comparison between optimized topologies of permanent magnet thrust bearings with back-iron 10046 <i>*Maxence Van Beneden, Virginie Kluyskens, Bruno Dehez (Universite catholique de Louvain), Belgium</i>
16:00 - 16:20	S4A2	Rotor Drop Analyses and Auxiliary Bearing System Optimization for AMB Supported Rotor/Experimental Validation - Part II: Experiment and Optimization 10128 <i>Jianming Cao, *Paul Allaire, Timothy Dimond (Rotor Bearing Solutions International), JJ. Janse van Rensburg (North-West University of Potchefstroom), Christian Klatt (CEROBEAR), USA</i>	S4B2	Simple and Effective Dynamic Model Identification Procedure of Magnetically Suspended Flexible Rotor Systems 10118 <i>Rami Levy, *Shai Arogeti (Ben-Gurion University of the Negev), Israel</i>	S4C2	Eigen frequency and damping in a passive magnetic bearing system 10042 <i>*Juan de Santiago (Uppsala University), Janaina G. Oliveira (Federal University of Juiz de Fora), Elkin Rodriguez (Federal University of Rio de Janeiro), Guilherme G. Sotelo (Fluminense Federal University), Magnus Hedlund (Uppsala University), Richard M. Stephan (UFRJ), Sweden</i>
16:20 - 16:40	S4A3	Planetary backup bearings for high speed applications and service life estimation methodology 10065 <i>*Lukas Querck, Benedikt Schuessler, Daniel Franz, Stephan Rinderknecht (Technical University Darmstadt), Germany</i>	S4B3	Nonlinear Control Type Magnetic Bearing for Adding Damping Force to Existing Rotor 10098 <i>*Yuichi Ariga, Yasumitsu Sakai (Yamagata University), Japan</i>	S4C3	Numerical Verification of Amplitude Reduction of a Rotor Supported by a Superconducting Magnetic Bearing Utilizing Internal Resonance 10140 <i>*Koki Kanda, Hiromu Sasaki, Masahiko Sasaki, Toshihiko Sugiura (Keio University), Japan</i>
16:40 - 17:00	S4A4	Research and experiment of auxiliary bearing for helium circulator of HTR-PM 10057 <i>*Guojun Yang, Zhengang Shi, Jingjing Zhao, Yan Zhou, Xingnan Liu, Ni Mo, Zhe Sun (Tsinghua University), China</i>	S4B4	Vibration reduction in a hollow-shaft rotor using flexibly-mounted internal-stator magnetic bearings 10162 <i>*Chris Lusty, Patrick S. Keogh (University of Bath), UK</i>	S4C4	Hysteresis in an axial rotating SMB used in the ring spinning process 10067 <i>*Anne Berger, Maria Sparsing, Gunter Fuchs (IFW Dresden), Mahmud Hossain, Anwar Abdkader, Chokri Cherif (Technical University of Dresden), Ludwig Schultz, Cornelius Nielsch (IFW Dresden), Germany</i>
17:00 - 17:20	S4A5	A performance analysis model with thermodynamic and superficial effects of the touchdown bearings in AMB systems 10031 <i>*Mindong Lv, Zixi Wang, Yuming Wang (Tsinghua University), China</i>	S4B5	Vibration control for active magnetic bearing high-speed flywheel-rotor system with inverse system method and two-degree-of-freedom PID control 10058 <i>*Chuan Mao, Liangliang Chen, Changsheng Zhu (Zhejiang University), China</i>	S4C5	Trial of Large Gap Using Superconducting Magnetic Suspension System 10146 <i>Akira Minoda, *Mochimitsu Komori, Kaoru Nemoto, Ken-ichi Asami, Nobuo Sakai (Kyushu Institute of Technology), Japan</i>